Characterizing and constructing adjustment sets

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Joint work with Johannes Textor, Markus Kalisch and Marloes Maathuis

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Causal effects



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Estimate the total causal effect of X on Y

• $do(\mathbf{x})$: an intervention that sets variables **X** to **x**.

Observational data

Randomized control studies



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 the average change in Y due to do(x) from observational data.
- $do(\mathbf{x})$: an intervention that sets variables **X** to **x**.

Observational data

Randomized control studies





- PC (Spirtes et al, 1993), GES (Chickering, 2002), ARGES (Nandy et al, 2016).
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- Causal effects are often estimated by adjusted regression.
- Adjustment sets depend on the causal structure, which can be represented by a graph.

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- S is an adjustment set relative to (X,Y) in causal DAG D if for any f compatible with D:

$$f(\mathbf{y}|do(\mathbf{x})) = \begin{cases} f(\mathbf{y}|\mathbf{x}) & \text{if } \mathbf{S} = \emptyset, \\ \int_{\mathbf{S}} f(\mathbf{y}|\mathbf{x}, \mathbf{s}) f(\mathbf{s}) d\mathbf{s} = E_{\mathbf{s}} \{ f(\mathbf{y}|\mathbf{x}, \mathbf{s}) \} & \text{otherwise.} \end{cases}$$

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- The total causal effect of X on Y can be defined: $\frac{\partial}{\partial x} E(Y|do(x))$.
- In a linear setting the total causal effect of X on Y is then the linear regression coefficient of X in the regression Y ~ X + S.

Adjusting for too many or too few variables leads to bias.

Some intuition for DAGs:

- $(1) \qquad X \longrightarrow Z \longrightarrow Y$
- $(2) \qquad X \longleftarrow Z \longrightarrow Y$
- $(3) \qquad X \longleftarrow Z \longleftarrow Y$
- $(4) \qquad X \longrightarrow Z \longleftarrow Y$

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Answer: (1) \emptyset ; (2) {*Z*}; (3) {*Z*}; (4) \emptyset

Do not disturb causal paths, block all non-causal paths.

Which sets **S** are adjustment sets?

Some more intuition:



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Answer: \emptyset or $\{Z_2\}$

Descendants of nodes on a causal path (except of X) are forbidden.

(Each node is a descendant of itself)

R example



n <- 100000
eps <- matrix(rnorm(6*n,0,1), ncol=6)
X <- eps[,1]
Z1 <- 0.8*X + eps[,2]
Y <- 2*Z1 + eps[,3]
Z2 <- X + eps[,4]
Z3 <- Z1 + eps[,5]
Z4 <- Y + eps[,6]</pre>

The total effect of X on Y is $0.8 \cdot 2 = 1.6$.

R example

$$\begin{array}{cccc} x \xrightarrow{0.8} & Z_1 \xrightarrow{2} & Y \\ \downarrow & & \downarrow & & \downarrow \\ Z_2 & Z_3 & Z_4 \end{array}$$

- > lm(Y~X)\$coeff[2]
- 1.598732
- > lm(Y~X+Z1)\$coeff[2]
- 0.003260167
- > lm(Y~X+Z2)\$coeff[2]
- 1.596347
- > lm(Y~X+Z3)\$coeff[2]
- 0.7985709
- > lm(Y~X+Z4)\$coeff[2]
- 0.2730853
- > lm(Y~X+Z2+Z3)\$coeff[2]
- 0.7996412

Existing results for DAGs

- Back-door criterion (Pearl, 1993)
 - sufficient
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- Back-door criterion (Pearl, 1993)
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Given a DAG D, disjoint sets **X**,**Y** and **S** can **check** whether **S** satisfies back-door/adjustment criterion.

- The adjustment criterion will give you all adjustment sets.
- The back-door criterion will give you **some** adjustment sets.

DAG:



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Unknown causal directions (CPDAG):



DAG:



Unobserved confounders (MAG):



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Unknown causal directions (CPDAG):

Unobserved confounders and unknown causal directions (PAG):



$$X_1 \longrightarrow X_3 \longleftarrow X_5$$

DAG:



Unobserved confounders (MAG):

$$X_1 \longleftrightarrow X_3 \longleftrightarrow X_5$$

Unknown causal directions (CPDAG):

Unobserved confounders and unknown causal directions (PAG):



$$X_1 \bigcirc X_3 \longleftarrow X_5$$

Can be learned from observational data.

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- **CPDAG**: PC (Spirtes et al, 1993), GES (Chickering, 2002), ARGES (Nandy et al, 2016).
- **PAG:** FCI (Spirtes et al 1993, Zhang 2008), RFCI (Colombo et al, 2012), FCI+ (Claassen et al, 2013).

Overview of graphical criteria for adjustment

Can be learned from

observational data

	DAG	MAG	CPDAG	PAG
Back-door (Pearl '93)	\Rightarrow			
Adjustment (Shpitser et al '10)	\Leftrightarrow			
Adjustment (Van der Zander et al '14)	\Leftrightarrow	\Leftrightarrow		
Generalized back-door (Maathuis & Colombo '15)	\Rightarrow	\Rightarrow	\Rightarrow	\Rightarrow
Generalized adjustment (Perkovic et al '15)	\Leftrightarrow	\Leftrightarrow	\Leftrightarrow	\Leftrightarrow

\Rightarrow - sufficient, \Leftrightarrow - necessary and sufficient

Theorem (Perković et al, 2015): **S** is an adjustment set relative to (\mathbf{X}, \mathbf{Y}) and \mathcal{G} if: Amenability \mathcal{G} is **amenable** relative to (\mathbf{X}, \mathbf{Y}) . Forbidden Set **S** does not contain nodes in Forbidden $(\mathbf{X}, \mathbf{Y}, \mathcal{G})$.

Blocking **S** blocks all **proper non-causal definite status** paths from **X** to **Y** in *G*.

For any DAG/CPDAG/MAG/PAG \mathcal{G} and node sets **X**,**Y** and **S**, we can **check** whether **S** is an adjustment set relative to (**X**,**Y**).

(1) Does an adjustment set always exist?

(2) Can we construct adjustment sets using a fast algorithm?

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R package dagitty on CRAN.

(1) Does an adjustment set always exist? No.

Theorem (Perković et al, 2016)

There exists an adjustment set relative to (\mathbf{X}, \mathbf{Y}) and \mathcal{G} if and only if adjustmentSets $(\mathcal{G}, \mathbf{X}, \mathbf{Y}, type="canonical")$ returns a set.

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Yes.

Van der Zander et al, 2014 for DAGs and MAGs. Perković et al, 2016 for CPDAGs and PAGs.

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- isAdjustmentSet(G, S, X, Y) checks whether S is an adjustment set for (X, Y) and G in O(|V|+|E|) runtime.
- adjustmentSets(G, X, Y, type="all") lists all (or all minimal, if type="minimal") adjustment sets for (X, Y) and G in O(|V|(|V|+|E|)) runtime per set.

For CPDAGs and PAGs $\mathcal{G} = (\mathbf{V}, \mathbf{E})$ - the output of most causal structure learning algorithms - we developed:

- A necessary and sufficient graphical criterion for finding adjustment sets.
- An algorithm that finds an adjustment set relative to (\mathbf{X}, \mathbf{Y}) if there is one in $O(|\mathbf{V}| + |\mathbf{E}|)$ runtime.
- An algorithm that finds all (minimal) adjustment sets relative to (X, Y) in O(|V|(|V|+|E|)) runtime per set.

Thanks!

Joint work with Marloes Maathuis, Markus Kalisch, Johannes Textor



References:

- Perković, Textor, Kalisch and Maathuis (2015). A complete generalized adjustment criterion. UAI 2015.
- Perković, Textor, Kalisch and Maathuis (2016). Complete graphical characterization and construction of adjustment sets in Markov equivalence classes of ancestral graphs. *arXiv:1606.06903*.